

Stealth Assessment in Games to Measure and Support Learning

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Valerie Shute Florida State University

Games, Learning, Assessment

Claim 1

Good games can act as *transformative environments* to support skill development and deep, meaningful learning.

Claim 2

Learning is best when active, interesting, goal-oriented, and contextualized (i.e., features of good games).

Claim 3

Stealth assessment can collect dynamic evidence of learning in real-time, at various grain sizes (and use info to support learning).





Why Games as Assessment?

- Good games are *engaging* and require a player to *apply knowledge and skills* to succeed.
- Games are also *ubiquitous*. 75% of all U.S. households have at least one person who plays video games regularly (ESA, 2020).



Good Game Elements

- Interactive problem solving
- 2. Specific goals/rules
- 3. Adaptive challenges
- 4. Control
- 5. Ongoing feedback
- 6. Sensory Stimuli



Gestalt of Games



Control

The Hard Part

How can we increase learning in games without decreasing the fun?



Stealth Assessment Cycle



Stealth Assessment Features



When the cook tastes the soup, that's formative; when the guests taste the soup, that's summative.



Seamless & Ubiquitous

Formative as main purpose

Accurate & Rich Learner Models

Invisible assessment, transparent support!

Stealth Assessment Models (ECD)

Assessment Models & Metrics



Monitor & Diagnose Success

(adapted from Mislevy, Steinberg, & Almond, 2003)

Physics Playground

- Goal: guide a
 to a
 Everything obeys basic rules of physics (e.g., gravity, Newton's 3 laws).
- ✓ Two types of levels:

Sketching: player draws objects that "come to life" (e.g., pendulums, levers)

Manipulation: player changes physics parameters to solve levels.



BILL&MELINDA GATES foundation





The Team!

Physics Playground Video

Physics Playground—Competency Model Newton's 1st Law Force & **Motion** Newton's 2nd Law Newton's 3rd Law **Properties of Momentum** Linear Newtonian **Momentum Conservation of Momentum Physics Energy Can Transfer** Energy **Energy Can Dissipate Properties of Torque** Torque **Static Equilibrium**

Automated Scoring

Log Snapshot

```
"user id" : 294,
 "user fname" : "",
 "user lname" : "",
"session id" : 1,
"date" : "10\/23\/2012 17:50:14",
"token" : "51548bf0004b87a169a5f51caa8a27f5",
"trophies" : "L0-0: 0S 1G,L0-1: 1S 0G,L0-2: 0S 1G,L0-3: 0S 1G,L0-4: 0S 1G,L0-5: 1S 0G",
"event count" : 10,
"event 0" : {
           "type" : 0,
          "type string" : "Session Start",
          "time stamp" : 0
},
"event 1" : {
          "type" : 3,
          "type string" : "Enter Room",
          "time stamp" : 8.264,
          "room name" : "Playground 1"
},
"event 5" : {
          "type" : 2,
          "type string" : "Play Level",
          "time stamp" : 195.865997,
          "log file name" : "ALEXANDER 294 1 play4.replay",
          "level path" : ".//levels/\p0/\4 pendulum.level",
          "game time" : 62.523998,
          "pause time" : 0,
          "restart count" : 1,
          "object count" : 8,
          "object limit count" : 0,
          "nudge count" : 0,
          "erase count" : 0,
          "pin count" : 2,
          "agent vector" : "18.57 PO S 17600,27.65 PO S 26554,39.23 PO S 38368,59.33 PO S 58256,61.31 PS S 58256",
          "ball trajectory" : "<1.042, 0.549> <0.972, 0.545> <0.907, 0.564> <0.839, 0.590> <0.765, 0.618> <0.678, 0.651> <0.590, 0.676> <0.491, 0.687> <0.439, 0.691> <0.437, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.436, 0.691> <0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.446, 0.4
          "silver" : false,
          "gold" : true,
          "solved" : true
},
"event 6" : {
          "type" : 2,
          "type string" : "Play Level",
          "time stamp" : 267.790009,
```

Level-level log data

```
"time stamp": 12.163,
"level path": ".\\levels\\p4\\diving board.level",
"game time": 13 149.53,
"pause time": 1.54,
"restart count": 2,
"object count": 14,
"object limit count": 1,
"nudge count": 42,
"erase count": 13,
"pin count": 1.
"agent vector": "61.78 SB, 98.08 SB, 131.60 SB" ...
"ball trajectory": "<0.733, 0.427> <0.766, 0.394>...
"silver": true,
"gold": false,
"solved": true
```

Agent ID system

Agent	Monitor Trigger	Identify Trigger
Ramp	Event Ball touches Primary Object (PO)	Event Positive ID conditions met OR ball stops touching PO
	 Conditions Object has never rotated > 20 degrees 	 Conditions Object has never rotated > 20 degrees Ball moves along object: (>25% in horiz.) OR (>11% horiz. AND >4% vert.) OR (>4% horiz. AND >11% vert.)
Lever	Event Secondary Object falls on Object	Event ¾ seconds pass from Monitor Trigger
	 Secondary object has elevated downward momentum (vertical momentum <05 kg m/s) Object has <= 1 pin (attached to static object) Object has not moved much recently (less than 2% of screen in ¹/₃ sec) 	 Object has touched ball since Monitor Trigger Object has rotated > 20 degrees since Monitor Trigger Ball has reached an apex 4% higher than at Monitor Trigger
Pendulum Strike	Event Object touches ball Conditions • Object has 1 pin • Object has rotated > 20 degrees • Object has non-zero rotational velocity	Event % seconds pass from Monitor Trigger Condition • Ball moved moderately since Monitor Trigger (> 15% screen)
Springboard	 Event Object has elevated rotational velocity (>1.5 m/s) Conditions Rotating toward 12 o'clock (as opposed to 6 o'clock) Object has 2+ pins (attaches to a static object) 	 Event ¾ seconds pass from Monitor Trigger Conditions Object has touched ball since Monitor Trigger Ball has reached an apex 6% higher than at Monitor Trigger

Agent ID system

Agent	Monitor Trigger	Identify Trigger
Ramp	Event	Event
	Ball touches Primary Object (PO)	Positive ID conditions met OR ball stops touching PO
	Conditions	Conditions
	Object has never rotated > 20 degrees	 Object has never rotated > 20 degrees
		• Ball moves along object: (>25% in horiz.) OR (>11% horiz. AND >4% vert.) OR
_		(>4% horiz. AND >11% vert.)
Lever	Event	Event
	Secondary Object falls on Object	3/4 seconds pass from Monitor Trigger
	Constitutions	Conditions
	Conditions	Conditions
	Secondary object has elevated downward	Object has touched ball since Monitor Trigger
	Chiest has (4 sis (sttashad ta statis shist)	Object has rotated > 20 degrees since Monitor
	Object has <= 1 pin (attached to static object) Object has get merced events and the static object)	Timer
	Object has not moved much recently (less than 2%	Irigger
	of screen in 73 sec)	• Ball has reached an apex 4% higher than at Monitor Trigger
Pendulum	Event	Event
Strike	Object touches ball	¾ seconds pass from Monitor
SUIKE		
	Conditions	Trigger
	Object has 1 pin	Condition
	 Object has rotated > 20 degrees 	Ball moved moderately since Monitor Trigger (> 15% screen)
	Object has non-zero rotational velocity	
Springboard	Event	Event
	Object has elevated rotational velocity (>1.5 m/s)	¾ seconds pass from Monitor Trigger
	Conditions	Conditions
	Rotating toward 12 o'clock (as opposed to 6	Object has touched ball since Monitor Trigger
	o'clock)	Ball has reached an apex 6% higher than at Monitor Trigger
	Object has 2+ pins (attaches to a static object)	

Agent ID system

Agent	Monitor Trigger	Identify Trigger
Pendulum	Event	Event
Strike	Object touches ball	3/4 seconds pass from Monitor
	Conditions	Trigger
	 Object has 1 pin 	Condition
	 Object has rotated > 20 	Ball moved moderately since Monitor
	degrees	Trigger (> 15% screen)
	 Object has non-zero 	
	rotational velocity	

PP—Evidence Model

• Evidence Identification (EI): Establish rubrics to auto-score raw data (observables, aka "indicators") per level from log files.

• Cut Scores: Determine cut scores from frequency distributions of indicators.

• Evidence Accumulation (EA): During gameplay, data per indicator feeds into Bayes net (*one BN per level*).

For more, see R. Almond's Peanut suite of tools to generate BNs (<u>https://pluto.coe.fsu.edu/RNetica</u>).

Time to solve, object(s) drawn, sliders adjusted, # restarts, gold coin, levels solved, etc. (by level & session).





Stealth Assessment Steps



Stealth Assessment Steps (cont.)



Learning Supports



- Worked examples
- Game tutorial
- Hints
- Support tutorial

- Physics videos
- Interactive def's
- Animations
- Formulas
- Hewitt videos
- Glossary

- Encouragement Brea
- Growth mindset
- Praise

•

- Breathing exercise
- Store—change ball, music, background
- Rube Goldberg videos

Learning Supports



Learning Supports—Physics videos

Energy can Transfer

(Lever)

Research Study

- N = 263 (9th 11th graders), science class, 6 days with ~4 hr gameplay
- Sketching and manipulation levels (91 levels total)
- Full set of (8 different) learning supports
- Physics pretest and posttest
- Game and learning support questionnaire





For details, see: https://myweb.fsu.edu/vshute/pdf/JCAL2020.pdf

Research Questions



Psychometric qualities. Are stealth assessment measures *reliable, valid, and fair?*



Learning & enjoyment. Do kids, overall, *learn* physics from PP? Did they *enjoy* the game?



Learning supports. Which *learning supports* most effectively enhance learning and game performance?



Reliability (*n* = 263)

- Reliability of <u>external measure</u>: (Cronbach's α values), pretest = .77; posttest = .82; n = 263.
- Reliability of stealth assessment measures: CFA Gold coins by four agents: X²/df < 3, CFI > .95, RMSEA < .05, SRMR < .05
- *3.* Intraclass correlation = **.85** (Ramp, Lever, Pendulum, Springboard gold coins)
- 4. Cronbach's α of stealth assessment = .87 3
 (Data: gold coin info (NA, 0, 1); Valid Cases: 110 (out of 169); Levels: 29 (out of 74)





Physics Facets

Validity

Stealth Ass't Estimates	Pretest	Posttest
Physics (Overall) <u>EAP</u>	<mark>0.36**</mark>	<mark>0.40**</mark>
Force and Motion	0.29**	0.30**
Linear Momentum	0.27**	0.27**
Energy	0.22**	0.35**
Torque	0.14*	0.18**

Note. * *p* < .05; ** *p* < .01

Fairness (re: learning)

Same number of males and females with wide range of ethnicities.

RQ1

Learning by Gender. ANCOVA: post (DV), gender (IV), pre (Cov): Results showed *no significant outcome differences by gender* holding pretest constant: F(1, 195) = 0.04; p = .85.

Learning by Ethnicity. ANCOVA: post (DV),



ethnicity (IV), pre (Cov): Results showed *no significant outcome differences by ethnicity* holding pretest constant: F(2, 154) = 1.32; p = .27.

Learning & Enjoyment

- **Overall Learning**. Students scored significantly higher on posttest than pretest: F(1, 198) = 9.53; p = .002 after gameplay. Control group (no game) showed no pre/post diff ($M_{pre} = 11.6$; $M_{post} = 11.6$).
- Overall Enjoyment. Students really enjoyed the game (*M* = 4.03) on a 1-5 scale (1=hated; 5=loved).

RQ2

- By Gender: Males (*M* = 4.05) and females (*M* = 4.00) enjoyed it equally!
- By Ethnicity: Whites (M = 4.0),
 Blacks (M = 4.0), and Hispanics (M = 4.3) enjoyed it equally!



Learning Supports

RQ3

- Favorite supports. Hints, physics videos, and worked examples.
- **Predicting learning**. Regression: Posttest (DV), with pretest & all 8 support freqs in equation: Only pretest (β = .66) and Physics videos (β = .11) significantly predicted outcome: R^2 = .50; *F* (2, 198) = 97.6 (*p* < .001)
- **Predicting gameplay**. Those watching more Physics videos also did significantly better in the game than those watching fewer videos (re: levels completed, gold, and silver coins earned).
- Supports don't detract from fun. Students who watched more Physics videos reported higher levels of enjoyment than watching fewer. Enjoyment ($\beta = .18$, F(1, 193) = 6.23, p = .01).

Bonus Question!

Can stealth assessment be used in *existing* games to measure students' abilities?

Stealth Assessment in Commercial



- 1st stealth assessment (proof of concept)
- Measured *creative problem-solving skills*
- Merged cog & non-cog variables
- Used Bayes nets to accumulate estimates
- Shute et al. (2009). <u>Melding the power of serious</u> games and embedded assessment to monitor and foster learning: Flow and grow.



- Love this game!
- Measured problem-solving skills
- Used Bayes nets to accumulate estimates
- Validated stealth assessment to external measures
- Shute, et al. (2016). <u>Measuring problem solving skills via</u> <u>stealth assessment in an engaging video game</u>.

Stealth Assessment in Commercial





- Measured *calculus knowledge*
- Validated the stealth asst measure.
- Smith, G., Shute, V. J., & Muenzenberger, A. (2019). <u>Designing</u> and validating a stealth assessment for calculus competencies.



- Measured problem solving, spatial skill, & persistence before/after game
 <compared to Lumosity>
- Shute, V. J., Ventura, M., & Ke, F. (2015). <u>The power of play: The effects of Portal</u> <u>2 and Lumosity on cognitive and noncognitive</u> <u>skills</u>.



- Measured prob solving, causal reasoning, static equilibrium.
- Qualitative study supporting importance of failure re: learning.
- See: Shute, V. J., & Kim, Y. J. (2011). <u>Does</u> <u>playing the World of Goo facilitate learning?</u>.

LESSON LEARNED—Stealth assessment can be included in existing commercial games to measure important competencies!

Current & Next Steps

• Student vs. Computer Control of Supports. Recently tested student

vs. computer-delivery of supports on learning/engagement (IES). When optional, students don't get enough dosage so default now = computer delivered.

- **Timing of Support Delivery.** Should supports be delivered **before** a relevant game level (e.g., advance organizer) or **after** (for reflection & consolidation)? Currently tested 146 Ss with slight advantage for *after* (see: <u>https://myweb.fsu.edu/vshute/pdf/TIMING.pdf</u>).
- Affective Supports. Designed/developed/tested multiple affective supports to reduce frustration and increase persistence (e.g., music change, fun videos, motiv messages, mindfulness, secret store) (<u>https://myweb.fsu.edu/vshute/pdf/affect_support.pdf</u>)
- **Implement quit prediction model in the game.** Who is likely to quit a level? The model features 37 behavioral indicators with different weights. Will test the quit model in PP to trigger affective supports (<u>https://myweb.fsu.edu/vshute/pdf/ICQE_PP_Quit.pdf</u>).

Take-aways!

- (Most) everything is teachable. Some things we didn't think could be instructed (e.g., spatial ability, creativity, empathy, collaborative problem solving, persistence, etc.) can be! So, after perfecting meas't of competencies, focus on interventions to improve learning.
- **Feedback**. One of the most important parts of learning anything is feedback! But the type and timing of feedback used is key. More research is needed here.
- Make learning fun. <u>Test anxiety is real, engagement leads to learning, and current standardized</u> <u>tests are limited</u>. Consider using games (or engaging immersive environments) to measure & support targeted competencies!
- Theoretical foundation is key. For both measurement and support of learning, develop CMs at the outset, then associated "learning indicators" (evidence) and real-time scoring/updating methods (e.g., ECD for top-down approach). Later, exploratory methods can find additional learning indicators (e.g., EDM). Together these can support of learning.

Take-aways!

- **Bayesian networks**. The most effective way to measure/estimate (in real time) competency states at various grain sizes is via Bayes nets (I've used them since 1995). Measurements should be probabilistic & cumulative, not black/white (pass/fail). May use tallies, which are simpler.
- Psychometric qualities. Talk is cheap. Always validate your instruments if you want to make solid claims about learning!
- **Embrace principles of instruction & learning.** When <u>designing learning</u> <u>supports in games/engaging environments</u>, make sure to pay attention to first principles of instruction (Merrill), multimedia (Mayer), and motivation (Keller)!

Thank you!

Questions?

Email: <u>vshute@fsu.edu</u>

Website:



If we think of our children as plants... summative assessment of the plants is the process of simply measuring them. The measurements might be interesting to compare and analyze, but, in themselves, they do not affect the growth of the plants. On the other hand, formative assessment is the garden equivalent of feeding and watering the



Our Team!













Co-Pl













SMEs









RAs



2016 - 2021



Physics Test (examples)







Physics Test (near transfer)





PP Adaptivity Algorithm—Simplified

Start



Physics Playground—4 Conditions

Concepts arrayed by difficulty. Within a concept, levels differed by difficulty (combined game mechanics and physics). All Ss completed tutorials for both Sketching and Manipulation types. About 10 levels for each of the 9 concepts.

- Linear (lockstep order): <N1L> Levels 1, 2, 3, ... 10; <EcT> Levels 11, 12... 21; ...
- Adaptive (based on BN estimates): <N1L> Levels 1, 4, 10;
 <EcT> Levels 11, 13, 18
- Nonlinear: (free choice): <N1L> Level 1; <N3L> Level 80;
 <PoM> Level 35 ...
- **Control**: pretest and posttest only (no game).

	Newton's 1 st Law
	Energy Can Transfer
	Energy Can Dissipate
ťy	Properties of Momentum
Difficul	Conservation of Momentum
	Properties of Torque
	Static Equilibrium
	Newton's 2nd Law
↓	Newton's 3 rd Law

Learning

Learning by Condition.

ANCOVA with posttest as DV, condition as IV, and pretest as covariate showed *no significant outcome differences by condition*, holding pretest constant: F(2, 195) = 0.34; p = .71.

Condition	Pretest M (SD)	Posttest M (SD)
Adaptive	11.77 (3.4)	12.23 (3.7)
(<i>n</i> = 64)		Gain = 0 .46
Linear	11.82 (3.4)	12.41 (4.0)
(<i>n</i> = 68)		Gain = 0 .59
Nonlinear	11.88 (3.8)	12.72 (3.9)
(<i>n</i> = 67)		Gain = 0 .84
Control	11.61 (3.6)	11.60 (4.2)
(<i>n</i> = 64)		Gain = -0 .01

Learning Supports

• *Favorite supports*. Hints, physics videos, and worked examples.

RQ3

- **Predicting learning**. Regression: Posttest (DV), with pretest & all 8 support freqs in equation: Only pretest (β = .66) and Physics videos (β = .11) significantly predicted outcome: R^2 = .50; *F* (2, 198) = 97.6 (p < .001)
- **Dosage**. Students who watched more Physics videos learned significantly more physics and did better in the game than those who watched fewer animations (for DV's: posttest, levels completed, gold, and silver coins earned).
- Supports don't detract from fun. Students who watched more Physics videos reported higher levels of enjoyment than watching fewer. Enjoyment (β = .18, F(1, 193) = 6.23, p = .01).

- Posttest (holding pre constant): $(\beta = .11; t = 2.11, p = .04, R^2 = .50).$
- Levels completed ($\beta = .43$, F(1, 197) = 45.15, p < .001, $R^2 = .18$),
- Gold coins earned (β = .35, F(1, 197) = 27.84, p < .001, R² = .12)
- Silver coins earned ($\beta = .31, F(1, 197) = 21.42, p < .001, R^2 = .10$).

Expected A Posteriori (EAP)

- For every node in physics CM, there's a triplet of current estimates: p(High), p(Medium), p(Low) with values summing to 1.
- To get a single number from triplets, we can assign weights (e.g., +1 * p(H); 0 * p(M); -1 * p(L)) which reduces to p(H) p(L).
- EAPs range from -1 to +1 like correlations.



Augmented Q-Matrix 🛛 Bayes nets

- Q-matrix: Set up relations among all levels (> 150), their targeted physics concept, difficulty, etc.
- Indicators: Specify "indicators" (measurable behaviors in the game) per task type (sketching vs. manipulation)
- Evidence Identification (EI): Establish rubrics to automatically score raw data per level from log files (e.g., number restarts, gold trophy <0/1>).
- 4. **Cut Scores**: Determine cut scores from frequency distributions of raw observables.
- 5. **Evidence Accumulation** (EA): For each indicator, create Low, Med, High levels to feed into Bayes net.
- 6. Generation of BNs. Used Almond's Peanut suite of tools to generate BNs (<u>https://pluto.coe.fsu.edu/RNetica</u>).

(not expected to be viewable)

	can be solved by:	Newton's 1st Law	Newton's 2nd Law	Newton's Brd Law	Properties of Momentum	Conservation of Linear Momentum	Energy car Transfer	Energy can Dissipate	Properties of Torque	Equilibriu	Iterative Design	GM (1-5)	PU (1-5)	Composite Difficulty Score	Term	
Balance	Manipulation		2 1		0) () (0	0	()	4	1	S	force	
Blocked by Blocks	Manipulation	() 1	1 0	0) () :	. 0	0	()	3	2	5	dissipativ	e force
Break the maze	Manipulation	() 2	2 0	1) (0	0	()	3	2	5	N 1st L	
roken Guitar	Manipulation	() 2	2 (1	. () (0	0	()	2	2	4	momentu	m
ookie Monster	Manipulation	() 3	2 1	. 0) () (0	0	()	2	1	3	free-fall	
ominos	Manipulation	() () (0) () :	1	0	()	. 1	2	3	dissipativ	e force
ireworks	Manipulation	() () 1	. 0) () (2	0	()	4	2	6	energy ca	n dissipate
lorida	Manipulation	() () 2	. 0) () (1	0	()	2	2	4	dissipativ	e force
rog	Manipulation	() () 2	. 0) (0 (1	0	()	3	2	S	N 3rd L	
ighthouse	Manipulation	1	L C) 2	. 0	0	0 (0	0	0)	3	1	4	N 3rd L	
ollipop	Manipulation	() () (0) () () (2	1	Ĺ	3	3	6	equilibriu	m
Aobile	Manipulation	() () (0) () () (2	1	L	2	3	S	equilibriu	m
lum Blossom	Manipulation		1 3	2 (0) () (0	0	()	2	1	. 3	force	
helves	Manipulation	() () (2) :	. 0	0	()	. 2	3	5	torque	
kate Park	Manipulation	() () (0) () :	1	0	()	1	2	3	dissipativ	e force
ocks	Manipulation	() 2	2 (0) () (1	0	()	2	2	4	velocity	
pring	Manipulation	1	2 () (1	. () (0	0	()	2	2	4	inertia	
ricks	Manipulation	() () (0) () (2	0	1	L	. 2	4	6	accelerati	on
IF02	Manipulation	1	ι () 2	: 0) () () (0	()	2	1	3	coefficien	t of restitution
Vhale	Manipulation		2 () (0) () (1	0	()	3	2	S	energy ca	n dissipate
round the Tree (P3)	R	3		0 0	0	0			0	()	2	2	4	GPE	
cosmic Cave (P6.11)	L/SB) () (0) () ;	. 0	1	()	- 4	4	8	N 2nd L	
ownhill (P2)	R		1 0) (0	0) :		0	()	1	2	3	N 1st L	
reen Appple (prev Torque)	Sketching) () (0	0) (0 0	1		2	3	3	6	mass	
leavy Blocks (P4)	L/P	1	ι () (0) () (0	2	0)	3	2	5	kinematic	s
ittle Mermaid (P3)	SB	() () (0) () :	. 0	0	()	2	2	4	energy ca	n transfer
(ature (P7)	L	() () (0	0)		1	()	5	4	9	ME	



Augmented Q-Matrix

٨	R	C	D	F	F	G	н	Î. î	1	K	1	м	N	0	D	0	P	ç
A	D	U.	0	5	r.	0	п		,	N	L	IVI	N	0	F	ų	n	3
					Properties	Conservation	n							Composite				
	can be solved	Newton's	Newton's	Newton's	of	o <mark>f</mark> Linear	Energy can	Energy can	Properties	Equilibriu	Iterative			Difficulty				
1	by:	1st Law	2nd Law	3rd Law	Momentum	Momentum	Transfer	Dissipate	of Torque	m	Design	GM (1-5)	PU (1-5)	Score	Term			
2 Balance	Manipulation	2	1	0	0	(0 0	C) 0	C)	4	1	L 5	force			
3 Blocked by Blocks	Manipulation	0	1	0	0	() 2	0) 0	0)	3		2 5	dissipativ	e force		
4 Break the maze	Manipulation	C	2	2 0	1	(0 0	C) 0	C)	3		2 5	N 1st L			
5 Broken Guitar	Manipulation	0	2	2 0	1	(0 0	0	0 0	0)	2		2 4	momentu	m		
5 Cookie Monster	Manipulation	0	2	2 1	0	(0 0	0	0 0	C)	2		3	free-fall			
7 Dominos	Manipulation	0	0) 0	0	() 2	1	0	C)	1		2 3	dissipativ	e force		
8 Fireworks	Manipulation	C	0	1	0	(0 0	2	2 0	C)	4	1	2 6	energy ca	n dissipate		
9 Florida	Manipulation	0	0) 2	0	(0 0	1	0	0)	2		2 4	dissipativ	e force		
0 Frog	Manipulation	C	0) 2	0	(0 0	1	0	C)	3		2 5	N 3rd L			
1 Lighthouse	Manipulation	1	. 0) 2	0	(0 0	C) 0	C)	3		4	N 3rd L			
2 Lollipop	Manipulation	C	0) 0	0	(0 0	0) 2	1	L	3		6	equilibriu	m		
3 Mobile	Manipulation	0	0) 0	0	() 0	0) 2	1		2	2	3 5	equilibriu	m		
4 Plum Blossom	Manipulation	1	. 2	2 0	0	() 0	C) 0	C)	2		3	force			
5 Shelves	Manipulation	C	0) 0	2	() 1	. 0) 0	0)	2	2	3 5	torque			
16 Skate Park	Manipulation	C	0) 0	0	() 2	1	0	C)	1		2 3	dissipativ	e force		
7 Socks	Manipulation	C	2	2 0	0	(0 0	1	0	0)	2		2 4	velocity			
8 Spring	Manipulation	2	. 0) 0	1	() ()	C) 0	C)	2		2 4	inertia			
9 Tricks	Manipulation	C	0) 0	0	(0 0	2	2 0	1	L .	2	2	4 6	accelerati	on		
UFO2	Manipulation	1	. 0) 2	0	(0 0	C) 0	C)	2	1	L 3	coefficier	t of restitu	tion	
1 Whale	Manipulation	2	. 0) 0	0	(0 0	1	0	0)	3		2 5	energy ca	n dissipate		
2																-		
3 Around the Tree (P3)	R	1	. 0) 0	0	() 2	0) 0	0)	2		2 4	GPE			
24 Cosmic Cave (P6.11)	L/SB	0	0) 0	0	() 2	0) 1)	4		4 8	N 2nd L			
5 Downhill (P2)	R	1	. 0) 0	0	() 2	0) 0	()	1		2 3	N 1st L			
6 Green Appple (prev Torque)	Sketching	C	0) 0	0	(0 0	C) 1	2	2	3		3 6	mass			
27 Heavy Blocks (P4)	L/P	1	0	0	0	(0	0	2	0)	3		5	kinematio	s		

: Back!